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Semi-Annual Status Report

0n

"A Theoretical Investigation of Wing Rocking"

(NASA-CR-165058) A THEORETICAL N82-15031
INVESTIGATION OF WING RCCKING Semiannual
Status Report, 1 Jul. - 31 Dec. 1981 (Kansas
Univ. Center for Research, Inc.) 36 p
Unclas
HC A03/MF A01 CSCL 01A G3/05 08716

NASA Grant NAG 1-134

July 1, 1981 - December 31, 1981

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EFFECTS OF VORTEX BREAKDOWN ON LONGITUDINAL AND LATERAL DIRECTIONAL AERODYNAMICS OF SLENDER WINGS BY THE SUCTION
ANALOGY

Ъу

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INTRODUCTION

Theoretical investigation of the breakdown of an isolated vortex has been conducted before (Refs. 1 and 2). However, its application to slender-wing aerodynamics is quite limited in scope and versatility (Ref. 3). In fact, very few correlations with data have been reported. In addition, these available theoretical methods require lengthy computer time and hence, are not suitable for applications in a preliminary design.

In this paper, a semi-empirical method to predict effects of vortex breakdown on aerodynamic characteristics of slender wings is described. The method is based on Polhamus' method of suction analogy. Both longitudinal and lateral-directional characteristics can be predicted.

THEORETICAL DEVELOPMENT

In the method of suction analogy, the vortex lift is equated to the edge suction force in the attached flow. It was observed by Lamar (Ref. 4) that for delta wings the angles of attack for vortex breakdown at the trailing edge ($\ll_{\rm BDTE}$) can be related to the leading-edge suction discribution ($G_{\rm S}C$). For a large $\ll_{\rm BDTE}$, the $G_{\rm S}C$ - distribution tends to peak out at a more outboard location (Fig. 1). However, the location of $(G_{\rm S}C)_{\rm max}$ itself is not a good correlation parameter because for lower swept wings, such as the 60-deg. delta, th peak location is less distinguished.

Therefore, the method to be developed must (1) employ a good correlation parameter for α_{SDTS} applicable to most planforms, not just delta wings; (2) be able to predict the progression of the breakdown point when α_{SDTS} ; and (3) predict the amount of remaining vortex lift in the region of breakdown. These are described in the following for both longitudinal and lateral—directional aerodynamics.

Longitudinal Aerodynamics

Let
$$\overline{\zeta} = \frac{\zeta_i C}{\overline{c} \sin^2 \alpha} \tag{1}$$

where \overline{c} is the mean aerodynamic chord. Since C_{S} is proportional to Sin^{2} C_{S} , it follows that $\overline{C_{S}}$ is a function of planform and Mach number only. If $\overline{C_{S}}$ is the nondimensional centroid location of the $\overline{C_{S}}$ - distribution from inboard to \overline{J} G_{IBM} , it was found that \overline{J}_{S} correlated well with experimental C_{SP} as shown in Fig. 2. The relation between \overline{J}_{S} and \overline{J}_{S} is illustrated in Fig. 1. The experimental C_{SP} are taken from Reference 5. The correlation curve in Fig. 2 was obtained by a least-square analysis of Wentz data (Ref. 5) and can be described as follows,

$$d_{BPTE} \cong 380 \text{ dog.}$$
, if $\overline{X} \geq 3.5$ (2b)

In Reference 5, the progression rate of the breakdown point on delta wings was also measured. Note that the progression rate

measured in the water tunnel is somewhat different from that in the wind tunnel (Ref. 6). Although the experimental progression rate is slightly different for different delta wings (Fig. 3), for simplicity, a single curve obtained by a least-square analysis of Wentz data is used in the present analysis. The curve can be described by

$$\Delta \vec{X} = 0.0070 \text{ and } - 0.0010 (and)^2 + 0.0003 (and)^3 - 0.0007 (and)^4$$

$$+ 0.0007 (and)^5, \text{ if and } < 8.0 \text{ dog.} \qquad (3a)$$

$$\Delta \overline{\chi} = \alpha s s s \gamma_2 + 0.03 > 6 \Delta e^2, \quad \text{if } \Delta d \geq Re d \gamma. \tag{3b}$$

and $\Delta \overline{\chi}$ is the nondimensional π - distance (referred to the root chotd) from the trailing edge to the breakdown point. The spanwise location of the breakdown point, $\overline{\chi}_{88}$, nondimensionalized with half span, can therefore be obtained as

$$\overline{y}_{ab} = 1.0 - 4\overline{\chi} \tag{5}$$

Once the vortex - breakdown point is located on the planform, it is necessary to determine the amount of remaining vortex lift after breakdown. It is well known that the vortex strength after breakdown is decreased, but not vanished. In other words, the sectional GG at any spanwise station $7 > 7_{60}$ must be multiplied by a factor & which is less than 1.0. To determine & , Wentz data for delta wings were analyzed at $26.5 \, \text{deg.}$ and compared with results by the Quasi-Vortex-Lattice Method (QVLM) (Ref. 7). The factor & is determined by requiring the QVLM results to match Wentz data as closely as possible through a least-square analysis.

The results are

$$k = 0.181 + 0.384 \frac{7}{8}$$
, if $\frac{7}{8} < \frac{1}{8}$
 $k = 0.981 - 0.28 \frac{7}{8} + 0.028 \frac{7}{8}^2$, if $\frac{1}{8} \le \frac{3.72}{8}$ (6)
 $k = 0.5$, if $\frac{7}{8} > 3.72$

The results indicate that different planforms (i.e. different y_{ℓ}) have different vortex characteristics after breakdown.

Lateral-Directional Aerodynamics

It was shown in Refs. 8 and 9 that in a sideslip, the leadingedge vortex on the windward side is pushed inward and downward,
thus inducing additional vortex lift; while on the leeward side, it
is pushed outward and upward, and thus inducing less vortex lift.

Note that the usual vortex lift, as explained through the suction
analogy, is produced by the existence of net upwash at the leading
edge, thereby inducing vortex separation. This is called the roll-up
type of vortex lift in the present analysis. On the other hand,
at a given of the sideslip does not change the net upwash at the
leading edge. Therefore, to account for the increase in vortex lift
on the windward side due to sideslip, a "displacement-type" vortex
lift must be introduced. The flow mechanisms and computational
methods for sideslip, yawing and rolling motions are described below.

(1) Vortex lift of the displacement type in sideslip

In general, the leading-edge thrust coefficient is given by (Ref. 10)

$$C_{t} = \frac{R}{2} \frac{C^{2} \sqrt{1 - M^{2} \cos^{2} \Lambda_{\theta}}}{\cos \Lambda_{\theta}} \tag{7}$$

where \mathcal{M} is the leading-edge sweep angle, and $\mathcal C$ is the leading-edge

singularity parameter defined as

$$C = \lim_{X \to X_{g}} \frac{1}{2} a C_{p} \left(\frac{x - x_{g}}{c} \right)^{\frac{1}{2}}$$
(8)

Now, in sideslip, & Gp is given by (Ref. 11)

$$\Delta G = 2\Delta \left(\frac{3\phi}{9\chi^2}\right) = 2\Delta \left(\frac{3\phi}{9\chi} \pm \frac{3\phi}{9\chi} 5ih^2\right) = 2\zeta_1 \pm 2\zeta_2 5ih^2$$

where χ' is the χ' -coordinate in the freestream direction and χ'_{χ} , χ'_{χ} are the components of vortex density in the χ' - and χ' - directions, respectively. The component, χ'_{χ} , is responsible for the longitudinal loading. Since the vorticity vector near the leading edge must be parallel to the leading edge, it follows that

$$Y_{R} \approx Y_{Y} \tan \Lambda_{I}$$
 (10)

near the leading edge. Hence, by substituting Eqs. (9) and (10) into (8), it is obtained that

$$C = C_{\alpha} (/ \pm \tan \Lambda_{g} \sin \beta)$$
(11)

where

$$C_{\alpha} = \lim_{\chi \to \chi_g} \chi_g \left(\frac{\chi - \chi_g}{c} \right)^{\chi_g}$$
(12)

is the leading edge singularity parameter due to ∞ for the symmetrical loading. Eq. (11) shows that the singularity parameter due to sideslip can also be interpreted as that produced by the interaction between $\mathcal{E}_{\mathcal{A}}$ and the sideslip velocity at the leading edge:

$$C_{\beta} = \lim_{\chi \to \chi_{\beta}} \chi_{\chi} \left(\frac{\chi - \chi_{\beta}}{c} \right)^{\frac{1}{2}} \sin \beta \tag{13}$$

By squaring Eq. (11) and substituting it into Eq. (7), the leadingedge thrust coefficient in sideslip can be obtained:

$$C_{e(p)} = \frac{\pi C_{e}^{2} (\pm 2 \tan \Lambda_{e} \sin \beta + \tan^{2} \Lambda_{e} \sin^{2} \beta) \sqrt{1 - M^{2} \cos^{2} \Lambda_{e}}}{2 \cos \Lambda_{e}}$$
(14)

The resulting thrust is in the direction pointing into the sideslip velocity (Fig. 4a). Hence, the corresponding suction coefficient $(G_{(p)})$ is

$$G_{S(\beta)} = \frac{C_{\pm}(\beta)}{\sin A_{\beta}} = G_{S(\alpha)} \left(\pm 2 \sin \beta + \tan A_{\beta} \sin^2 \beta \right) \tag{15}$$

where

$$C_{S(nl)} = \frac{\pi C_n^3}{3 \cos^3 \Lambda_l} \sqrt{1 - M^3 \cos^3 \Lambda_l}$$
(16)

is the suction coefficient for the symmetrical loading.

(2) Vortex lift of the displacement type in yawing

As shown in Fig. 4b, the induced sidewash at (x, y) is

$$P_{r} = -\frac{(\chi - \chi_{ref})}{b \sqrt{2}} \overline{r} , \quad \overline{r} = \frac{rb}{2V_{re}}$$
(17)

This sidewash varies over the planform, and hence gives rise to "variable sideslip" effect. According to Eq. (15), the corresponding suction coefficient ($\mathcal{C}_{S(P)}$) is then

$$G_{(n)} = G_{(n)} \left(\pm 2\beta_r + \beta_r^2 \tan \Lambda_\ell \right) \tag{18}$$

(3) Regions without potential flow effect

In the method of suction analogy, the vortex lift is added to the potential-flow lift to obtain the total lift. The potentialflow lift is calculated by summing all attached-flow pressure forces over the planform. This is used for the situation in which a vortex flow of the roll-up type is involved, such as in the symmetrical loading or due to rolling motion. For a vortex flow of the displacement type, a certain region near the edges has to be excluded in calculating the potential-flow component to avoid over-prediction.

According to Reference 12, the magnitude of $G_0 \subseteq G$ gives a good estimate of the location of vortex lift centroid from the leading edge. Hence, $G_{(p)} \subseteq G$ and $G_{(p)} \subseteq G$ are taken to be the streamwise distances measured from the leading edge to the vortex lift centroids for f and f modes of motion, respectively. In the present method, regions near the leading edge with f and f are assumed not to have the potential-flow effect. However, if the vortex breakdown is predicted to occur, the vortex flow region tends to enlarge, so that the symmetrical ($G_0 \subseteq G$) will be used.

(4) Boundary layer effect on Roll Damping

The rolling motion induces a change in local angle of attack so that the roll-up type vortex lift will be produced. Its calculation is described in Reference 7.

However, it is known that the conventional attached-flow theory tends to over-predict the roll damping by as much as 20% without accounting for the vortex flow (Ref. 13). One possible reason is that the boundary layer near the wing tip is thickened by the centrifugal effect in rolling, so that the effective angle of attack is reduced. For engineering applications, this effect will be accounted for in the following way.

Note that the boundary layer thickness is a function of skin

friction coefficient (). In Reference 14, a formula for the airfoil lift reduction due to boundary layer thickness is given as

$$\frac{\Delta G}{G} = -\frac{1}{4}\sqrt{G} \tag{19}$$

where & was chosen as 2.0. For a wing in steady rolling, it is assumed that Eq. (19) is applicable at the station of mean aerodynamic chord (MAC). According to Reference 15 (page 599), the thickness of a 2-D turbulent boundary layer can be written as

$$\delta_{\lambda} = 0.37 \, \pi_{2}^{4/2} \left(\frac{\nu}{V_{\infty}} \right)^{1/2} \tag{20}$$

where $\mathcal{H}_{\mathcal{E}}$ indicates that \mathcal{S}_{λ} is to be calculated at the trailing edge and \mathcal{J} is the kinematic viscosity. It follows that the slope of boundary layer is given by

$$\frac{dS_{s}}{dA_{t}} = 0.37 \times \frac{4}{5} \pi_{t}^{1/2} (\nu / \nu_{a})^{1/2}$$
(21)

According to Ref. 15(page 607), the boundary layer thickness on a rotating disk is given by

$$S_3 = 0.526 \sqrt{7}^{3/5} (\nu/\omega)^{1/5}$$
 (22)

where \overline{y} in the present application is taken to be the y - coordinate of MAC and ω is the rotating speed. It follows that

$$\frac{dS_3}{d\overline{y}} = 0.526 \times \frac{3}{5} \overline{y}^{-\frac{1}{2}} \left(\frac{y}{\omega} \right)^{\frac{1}{2}}$$
(23)

As shown in Fig. 5, in the present 3 - D applications, $\frac{dS_2}{dZ_2}$ is taken normal to the trailing edge. The effect of steady rolling is regarded as a small perturbation to the angle-of-attack effect,

so that only its component along the trailing edge will be accounted for. The angle, β_{ξ} , for the direction of combined slopes is then given by

$$\tan \beta_{\epsilon} = \frac{\frac{dS_{0}}{d\overline{g}}\cos \Lambda_{t}}{\frac{dS_{0}}{d\eta_{\epsilon}}} = \frac{\alpha \cos \Lambda_{x} \frac{\partial}{\partial t}\cos \Lambda_{t}}{\alpha \cos \Lambda_{x} \frac{\partial}{\partial t}\cos \Lambda_{t}} \left(\frac{\sqrt{\alpha}\eta_{t}}{\overline{g}^{2}\omega}\right)^{\frac{1}{2}}$$
(24)

However.

$$\omega \overline{y} = \frac{\omega b}{2V_0} \frac{V_0}{b/2} \overline{y} = \overline{P} \frac{\overline{y}}{b/2} V_0 , \overline{P} = \frac{\omega b}{2V_0}$$
(25)

Hence.

$$\frac{V_{\bullet}\chi_{t}}{\overline{y}^{2}\omega} = \frac{V_{\bullet}\chi_{t}}{\overline{P}(\frac{\overline{y}}{b/2})\overline{y}V_{\bullet}} = \frac{b/s}{\overline{y}}\frac{\chi_{t}}{\overline{y}}\frac{1}{\overline{P}}$$
(26)

Substituting Eq. (26) into Eq. (24), it is obtained that

$$\tan \beta_{\epsilon} = 1.0662 \cos \Lambda_{\epsilon} \left(\frac{1}{3} \frac{\chi_{\epsilon}}{3} \frac{1}{p} \right)^{1/2}$$
(27)

where

$$\chi_{t} = \overline{c} \, \omega s \, \Lambda_{t} \tag{28}$$

It is assumed that if Eq. (19) is for the angle-of-attack effect, then the combined effect, given by Eq. (19), is increased by a factor of 1/cos fe with fe given by Eq. (27). With the local angle of attack due to steady rolling, of, replacing for in Eq. (19). Eq. (19) is now rewritten as

$$\frac{\Delta d\rho}{\Delta \phi} = -2.2 \sqrt{c_f} \frac{\cos \hbar}{\cos \theta_c} \tag{29}$$

where the constant & is taken as 2.2, instead of 2.0, for a better

correlation with data, and ess/t is included for the notching effect of the trailing edge. That is, the component, $\frac{dS_3}{dS} \le h/t$, shown in Fig. 5 will make the trailing-edge boundary layer thinner.

(5) Rolling and yawing at non-zero sideslip

It was shown in Reference 8 that the roll damping of a slender wing at high angles of attack can be increased if the wing rolls about the stability axes at a non-zero sideslip. To explain this effect, let the total leading-edge singularity parameter be

where C_p , C_p and C_p are leading-edge singularity parameters produced by upwash (i.e. the roll-up effect), respectively. By squaring C to be used in Eq. (7), various cross-product terms appear. For the rolling motion, the vortex lift due to roll-up is further increased on the right wing due to inboard displacement of vortex core in positive sideslip. Similarly, any roll-up effect in the yawing motion will be further increased or decreased due to sideslip. However, products of any two roll-up effects or displacement effects do not produce forces and moments of the antisymmetrical nature. Hence, additional vortex-lift terms in the leading-edge singularity parameter due to rolling and yawing in sideslip are

$$C_{(pp)}^{2} = 2 C_{(p)} \left(C_{n} \tan \Lambda_{p} \sin \beta \right) \tag{31}$$

$$C_{(r\beta)}^{2} = \sum C_{(r)} (C_{c} \tan \Lambda g \sin \beta)$$
 (32)
Eqs. (31) and (32) are to replace C^{2} in Eq. (7) to produce the additional leading-edge thrust.

(6) Vortex breakdown in sideslip

In general, the angle of attack for vortex breakdown at the trailing edge in sideslip, & some , is reduced on the windward side and increased on the leaward side. The following steps are used to calculate of some in the present analysis.

- (a) Calculate $\frac{\pi}{2}$ from the symmetrical suction distribution ($C_{S(al)}$), except that the leading-edge sweep angle is taken to be $A_{I} \beta$ for the right wing and $A_{I} + \beta$ for the left wing.
- (b) Assume that the maximum vortex strength before breakdown for a given planform is unchanged by sideslip. Since the vortex strength is represented by C_s which is proportional to $\sin^2 c_s$, in follows that the maximum vortex strength will be reached at a lower c_s than c_{says} on the right wing because of increase in vortex lift in sideslip. Hence, c_says can be solved from the following equation

- (c) The vortex lift factor () is calculated by the same formula for (i.e. Eq. (6)), except that $\overline{\chi}_{(p)}$ is replaced by $\overline{\chi}_{(p)}$ calculated in step (a).
- (d) Whenever the vortex breakdown is predicted to occur at a given y station, Cs(a) must be multiplied by A. Therefore, the antisymmetrical vortex lift on the windward side due to sideslip would be given by

On the leeward side, the vortex breakdown may not occur at a given &.

In this case, the magnitude of the antisymmetrical vortex lift is the average of those on both sides.

(7) Vortex breakdown in yawing

The effect of yawing on vortex breakdown is similar to that due to sideslip. With a positive yawing, the left tip will be the first which is subject to possible vortex breakdown effect. Since the equivalent sideslip (\ref{p}) is variable along the leading edge, the average of \ref{p} at a given y station and that at the tip is used to determine \ref{k}_{BDTE} . For simplicity, \ref{k}_{BDTE} for the yawing motion is determined by a linear interpolation between \ref{k}_{BDTE} and \ref{k}_{BDTE} for sideslip.

(8) Vortex breakdown in rolling

Due to a positive roll, the local angle of attack on the right wing is increased. It would seem that the vortex-breakdown \ll would be decreased. However, rolling tends to move outboard the centroid of the vortex lift distribution (i.e. increasing \overline{y}_{ℓ}), so that the vortex-breakdown \ll is increased. In the present theory, it is assumed that \ll_{DTE} for the rolling motion is equal to \ll_{BDTE} for the symmetrical loading.

The average of the local \ll at a given y station and that at the tip is used to determine whether there is vortex breakdown at that station.

(9) Centroids of vortex lift

Based on the idea developed in Reference 12, c_sc gives the location of vortex lift centroid. Let leading-edge suction coefficients produced by upwash at the leading edge be denoted by $c_{s(p)}'$, $c_{s(p)}'$ and $c_{s(r)}'$. The roll-up for the antisymmetrical vortex lift is assumed to take place along a direction perpendicular to the leading edge. Hence, the antisymmetrical vortex lift of the roll-up type is assumed to act at

for the rolling motion, and at

for the yawing motion. In sideslip, it is at

This is illustrated in Fig. 6a.

On the other hand, if rolling and yawing motions take place in a non-zero sideslip, the vortex lift centroids will be at

For rolling and vawing motions, the inboard displacement of vortex lift centroids is further restricted by the position of symmetrical vortex lift centroids (i.e. $R = c_{\rm g}c$). Therefore, if

it is replaced by R $\cos \sqrt{\sin M_{\rm P}}$, where R cannot exceed the local chord. This is illustrated in Fig. 6b.

In a coming motion, rolling and yawing motions are coupled. The vortex lift centroid is then assumed to be that due to the rolling motion.

NUMERICAL RESULTS

Longitudinal Characteristics

Results for delta wings of 60°, 70° and 80° are presented in Figs. 7
10. The method for computing the vortex lift involving rounded leading edges is based on Kulfan's concept (Ref. 16). Note the differences in lift curves after vortex breakdown for different delta wings. The lift curve for the 80-deg. delta has a sharper change after vortex breakdown as compared with that for the 60-deg. delta. The lift curve for the 70-deg. delta wing represents the transition between these two types.

Lateral-Directional Characteristics

The effect of sideslip on the angle of attack for vortex breakdown at the trailing edge is presented in Fig. 11. The trend is correctly predicted, although the predicted magnitude is 2 to 3 deg. off.

The lateral characteristics for 60-deg. and 70-deg. delta wings are presented in Figs. 12 and 13, respectively. The predicted results agree well with data, except when α exceeds α _{BDTE} by 8 to 10 deg. In the latter situation, the effect of boundary layer separation must be accounted for and is not included in the present method.

Additional results are compared with data in Figs. 14, 15 and 16.

As shown in Fig. 15, the boundary layer correction is seen to be important for accurate prediction of roll damping. The change in slopes of and C, after vortex breakdown is due to the difference in breakdown of the for left and right wings.

Finally, the effect of sideslip on roll damping is illustrated in Fig. 17. With zero sideslip, the slope of $C_p - \overline{p}$ curve is always positive. This means that C_p is positive. On the other hand, as the sideslip is increased in a steady roll, C_p may become negative, as shown by the curve

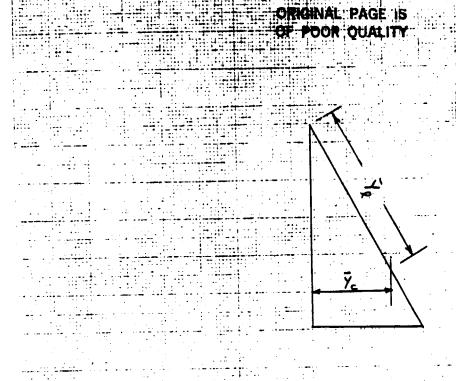
representing $\beta=10^{\circ}$. At $\beta=5^{\circ}$ and small \bar{p} , there is some discrepancy between the theory and data.

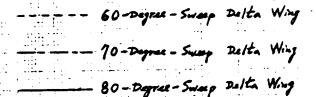
Extension of the theory to other planform shapes is currently being investigated.

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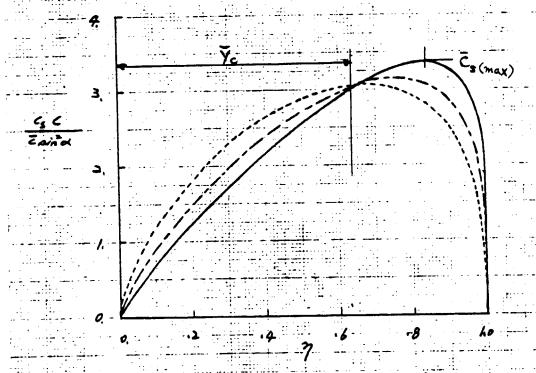


Fig. 1 Londing-Edge Section Distributions of Delta Wings with Sharp Leading Edges

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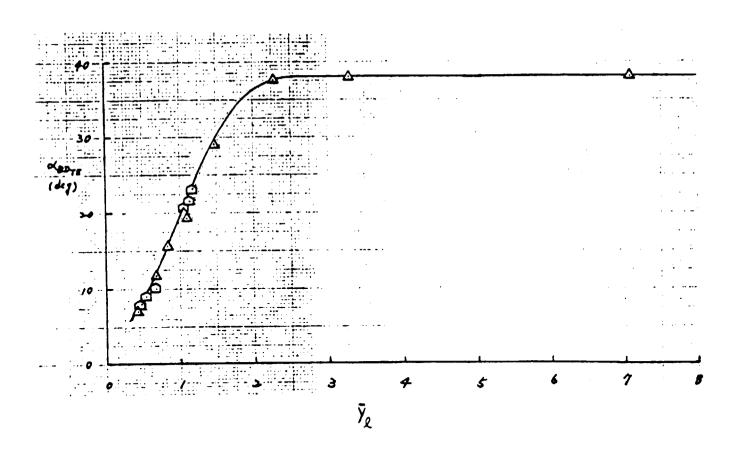


Figure 2. Correlation for Angles of Attack with Vortex Breakdown at the Trailing Edge

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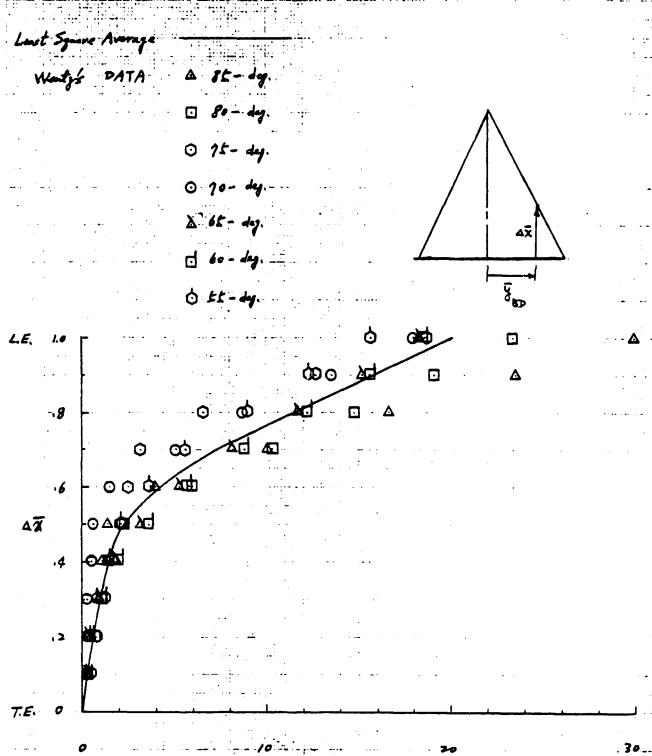


Figure 3. Vortex Brankdown Prograssion on Delta Wings in Air

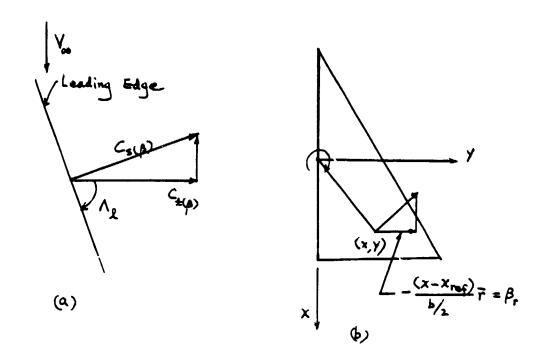


Figure 4 Sideslip Induced Suction and Variable Sideslip due to Yaw

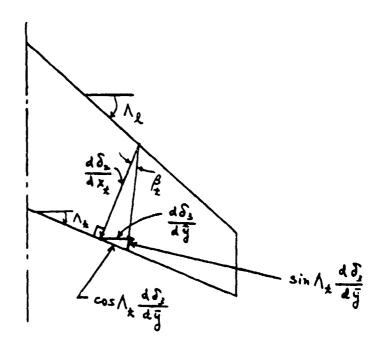
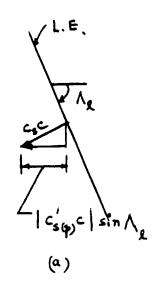


Figure 5 Boundary Layer Surface Slopes due to Angle of Attack and Steady Rolling.



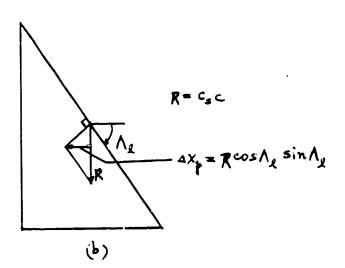


Figure 6. Inboard Displacement of Vortex List Centroids in Rolling Motion

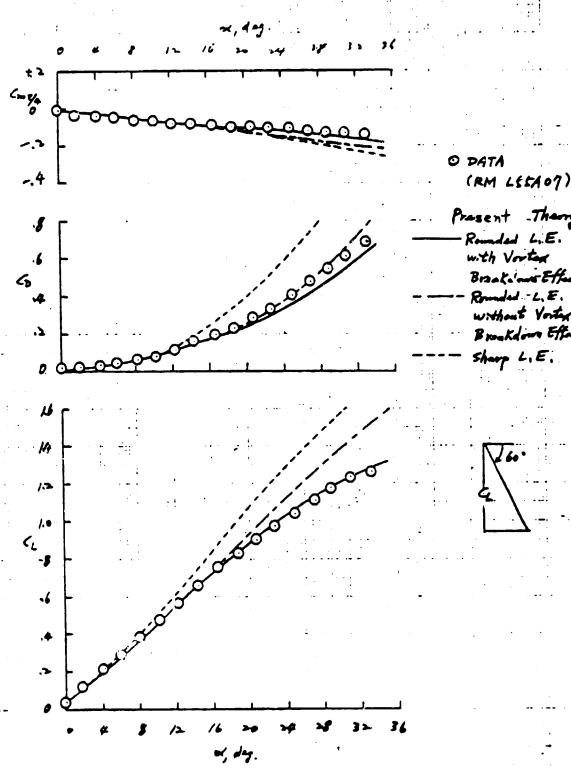


Figure 7 Longitudinal Acrodynamic characteristics of a Dotta Wing of 1 = 2,309 with Rounded Leading Edges.

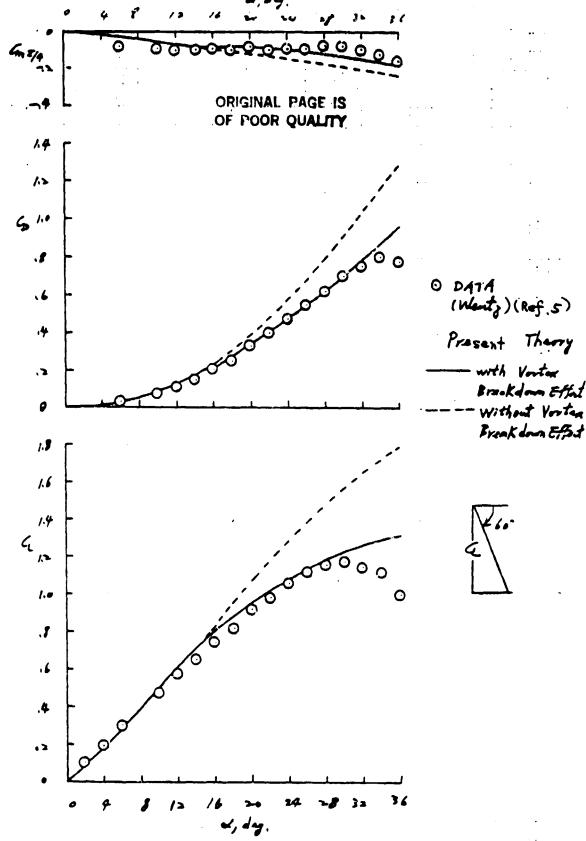


Figure 8 Longitudinal Accordynamic characteristics of a Delta Wing of A = 2.309 with Sharp Leading Edges

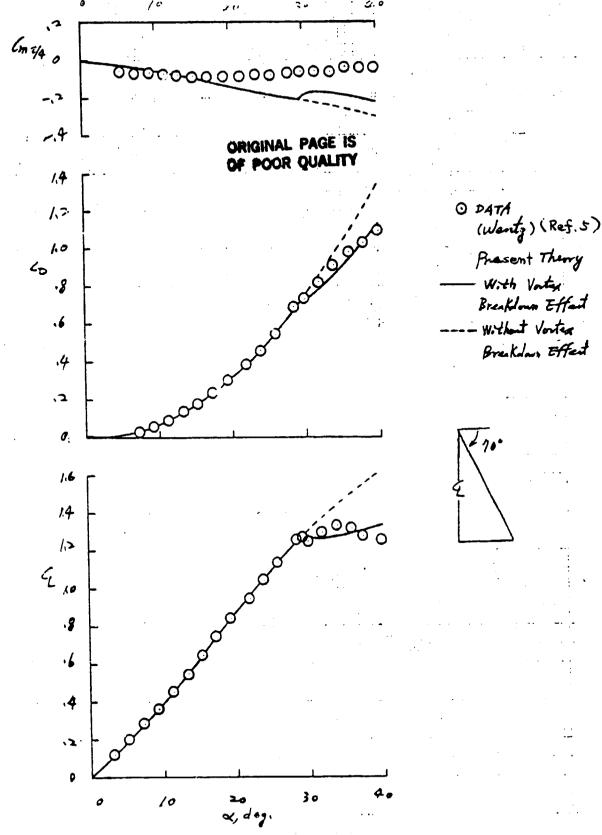
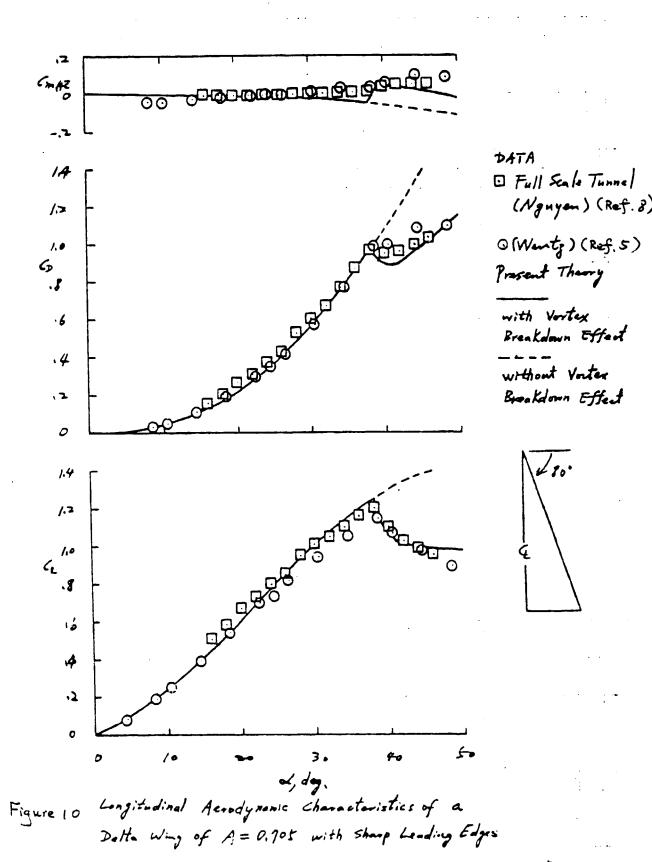
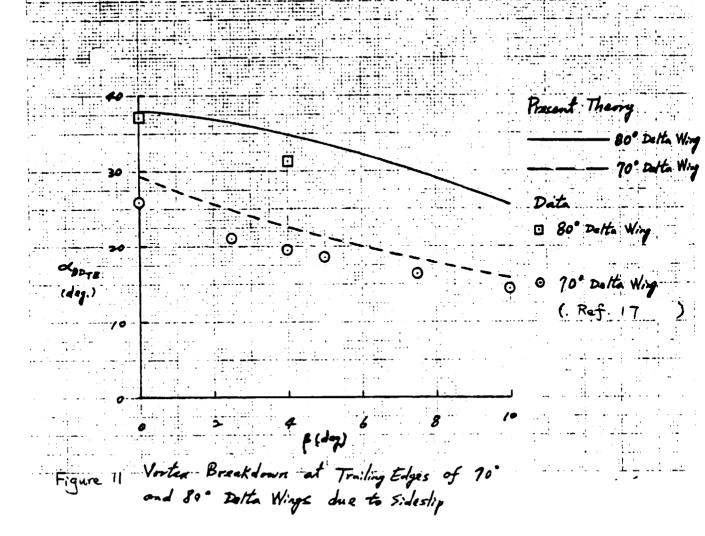
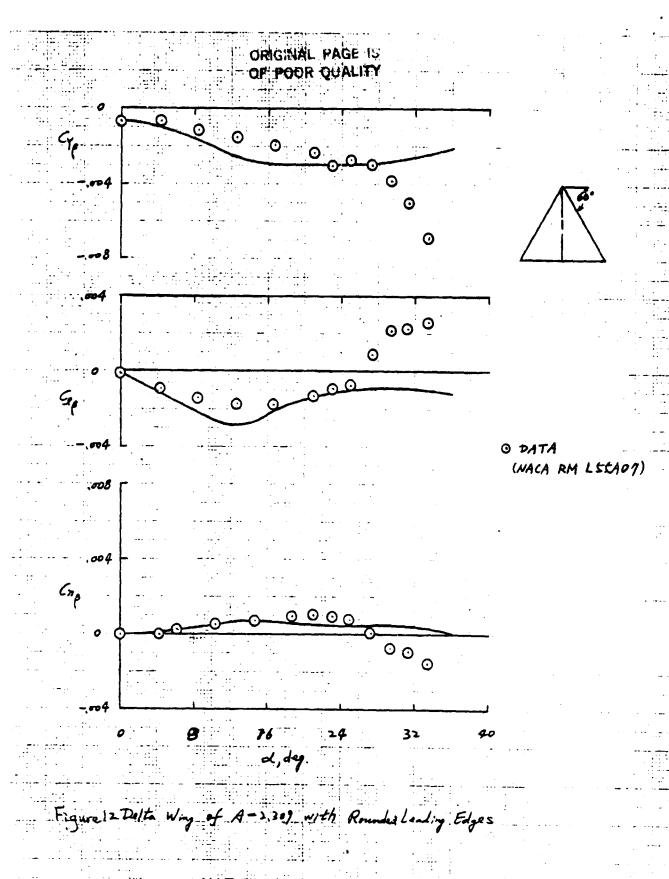


Figure 9 congitudinal Aerodynamic characteristics of a Delta Wing of A= 1.416 with Sharp Leading Edges





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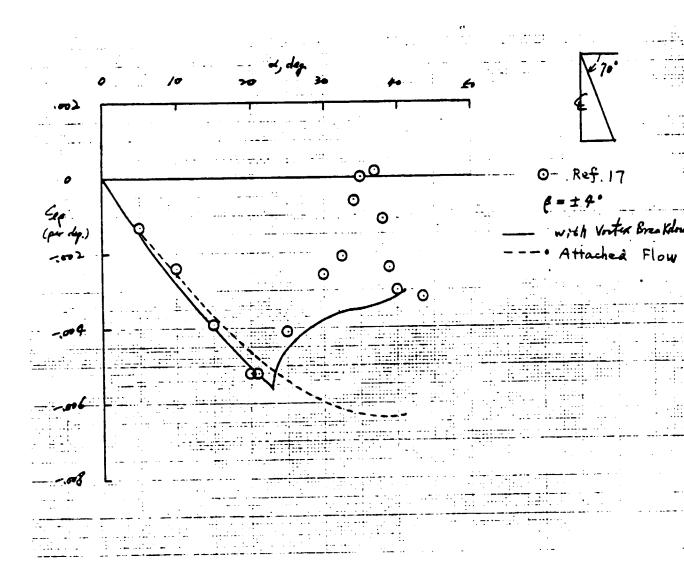
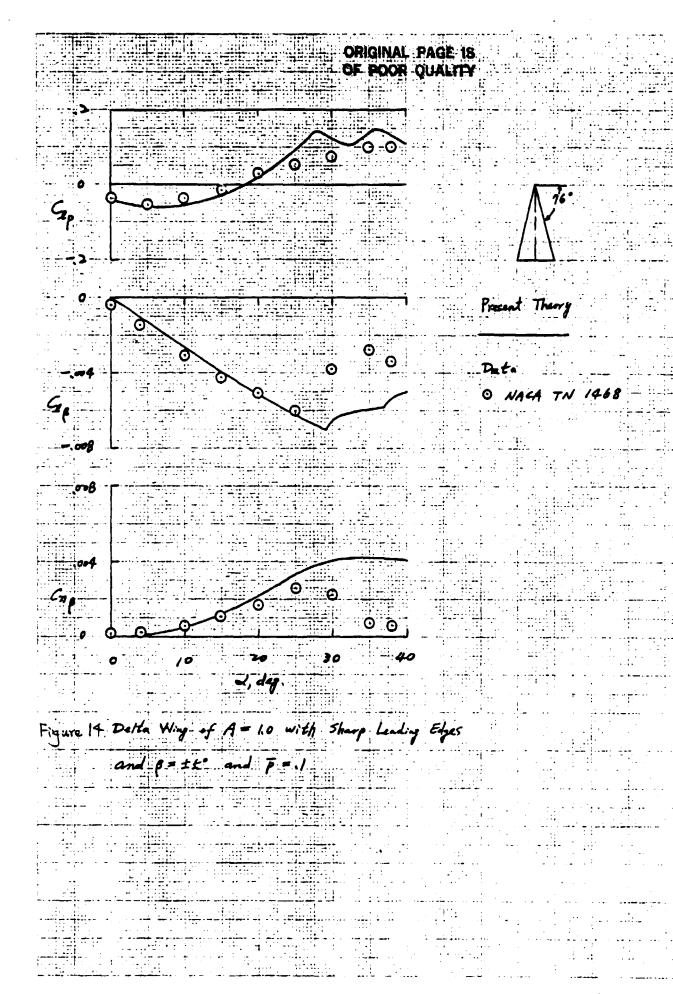
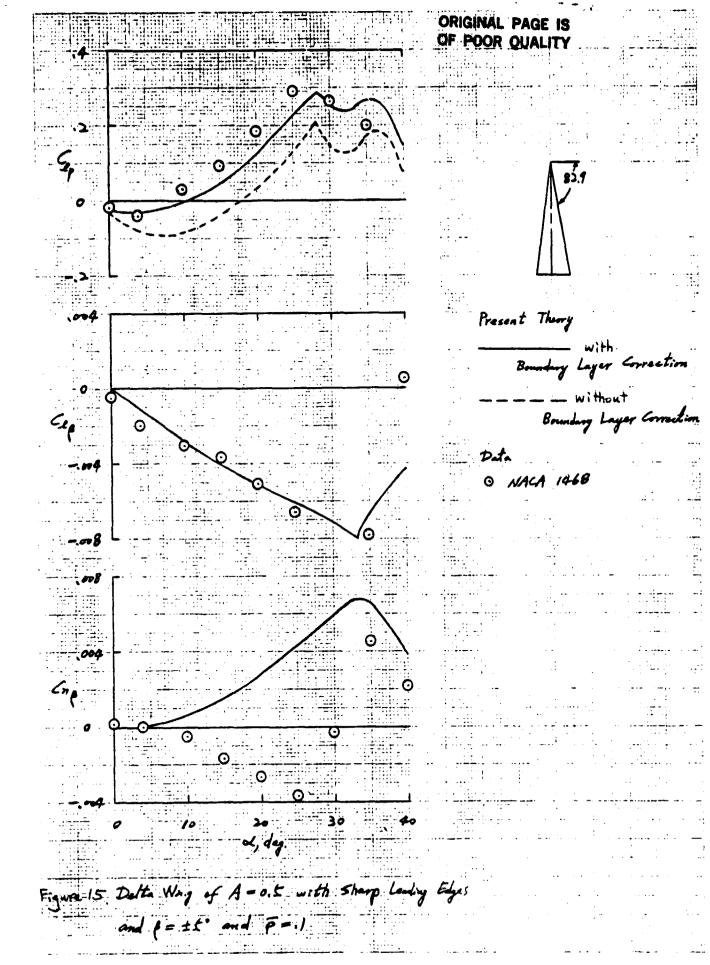


Figure 13. Delta Wing of A= 1.46 with Sharp Leading Edges





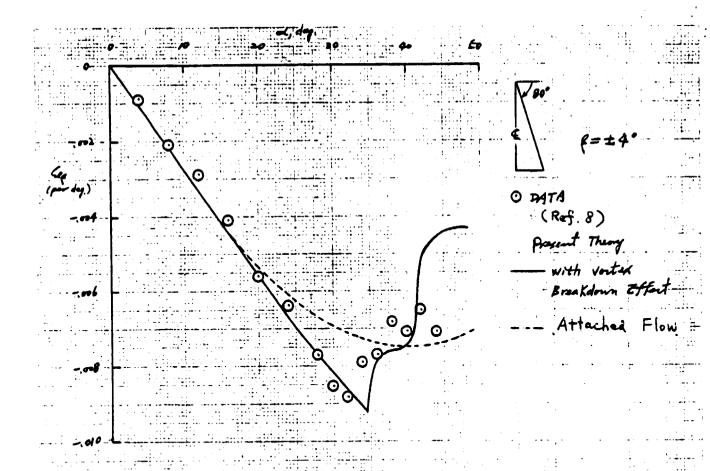
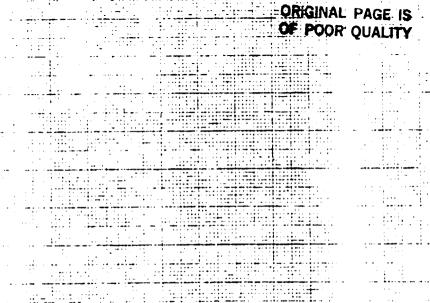


Figure 16. Lateral - Stability Derivative with of for a

Detta Wing of A = 0.70 f with Sharp Loading Edges with B=±4°



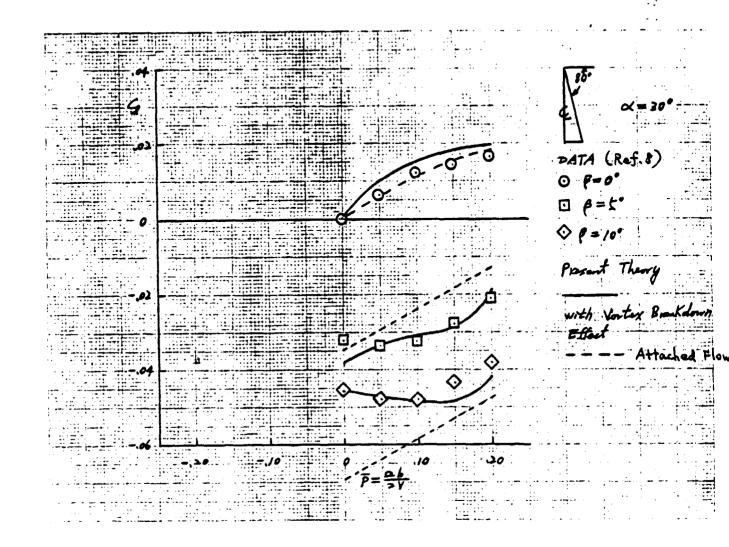


Figure 17. Effect of Sideslip on Roll Damping